

C u r r i c u l u m V i t a e S t e f a n o R o s a

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Qualification Summary

Research and working experience in estimation and optimization for autonomous navigation of mobile robots (multi-robot localization, SLAM, path planning, task allocation), computer vision for robotics, human-machine interaction, assistive technologies.

Education

Jan. 2011 to Apr. 2014: Ph.D. in Mechatronics

Institution: IIT Istituto Italiano di Tecnologia, Genova, Italy and
Politecnico di Torino, Turin, Italy

Dissertation: Localization and Mapping for Service Robotics Applications

Sep. 2005 to Jan. 2008: M.S. in Computer Engineering

Institution: Politecnico di Torino, Turin, Italy

Sep. 2002 to Sep. 2005: B.S. in Computer Engineering

Institution: Politecnico di Torino, Turin, Italy

Employment

Oct. 2016 to present: PostDoc Researcher

Institution: University of Oxford

Topics: Long-term localization and navigation of robots and people in GPS denied environments using fusion of visual and non-visual opportunistic signals. Using robot navigation experiences to assist in human localization and navigation, and vice versa with cross-modality training. Learning intuitive physics for robot interaction.

Projects:

- ESPRC programme grant "Mobile Robotics: Enabling a Pervasive Technology of the Future" (EP/M019918/1)

Jan. 2012 to 2016: Research fellow

Institution: Politecnico di Torino - Telecom Italia Joint Open Lab, Turin, Italy

Topics: Robust Simultaneous Localization And Mapping (SLAM) for industrial service robotics, visual-based localization, object detection and pose estimation for pick and place

Projects:

- HOTBOT, an autonomous mobile robot for data center hotspot detection
- FLY4SMARTCITY, a cloud-robotics service in a smart city scenario for emergency management using small Unmanned Aerial Vehicles (UAVs)
- VIRGIL, a tele-presence museum tour-guide robot
- PARLOMA, a low-cost robotic hand for remote communication between deaf-blind users

Jan. 2011 to Apr. 2014: Ph.D. student in Mechatronics

Institution: Istituto Italiano di Tecnologia, Genova, Italy and
Politecnico di Torino, Turin, Italy

Topics: Laser-based long-term localization and SLAM for service robotics; 3D computer vision algorithms for space robotics applications

Projects:

- Development of a system for astronaut's body mass estimation using a vision sensor in microgravity environments
- Space debris detection using wide-baseline stereo cameras

Jan. 2008 to Dec. 2010: Research fellow

Institution: Politecnico di Torino, Turin, Italy

Topics: Design and implementation of algorithms for mobile robot localization, sensor fusion, vision-based SLAM, Wi-Fi based communication, path-planning and video surveillance

Projects:

- MACp4LOG: a mobile robotic platform, with on-board vision systems and sensors, integrating a flexible wireless communication solution, for monitoring and surveillance in logistic environments

May. 2005 to Dec. 2005: Java developer

Company: E-Mentor S.r.L.

Project:

- Development of graphical user interfaces for e-learning platforms and development of a role playing game for e-learning

Professional Activities

Speaker: Approcci innovativi e applicazioni della visione artificiale, Aosta, November, 2010; EuroScience Open Forum - ESOF, Turin, July, 2010; invited speaker at StrongMar Winter School, Edinburgh, 2018

Reviewer for int. journals and conferences: Transactions on Robotics T-RO, Transactions on Industrial Informatics TII, Journal of Intelligent & Robotic Systems; Intelligent Service Robotics; International Conference on Robotics and Automation - ICRA; International Conference on Intelligent Robots and Systems - IROS; Conference on Decision and Control - CDC

Co-Founder: Hotblack Robotics, 2016 (Open-Source Cloud Robotics solutions), EWavee, 2013, Wi-Fi localization services

Assistant lecturer for Automatic Control, Politecnico di Torino, 2013;
Basics of Automatic Control, Politecnico di Torino, 2012; Robotics, Politecnico di Torino, 2013-2015

Lecturer for Ph.D. course: Research topics in computer and control engineering - Introduction to probabilistic robotics, Politecnico di Torino, 2010-2012

Awards

National Award for Innovation - Premio Perotto Zucca
Startup Weekend Turin 2013 - Mind the Bridge grant

Languages

English: fluent (speaking, reading, writing), IELTS; **French:** basic

Publications

Journal papers

1. Rosa S., Toscana G., Bona B. **Q-PSO: Fast Quaternion-based Pose Estimation From RGB-D Images**, Journal of Intelligent and Robotic Systems, 2017, DOI: 10.1007/s10846-017-0714-3
2. Anjum M.L., Rosa S., Bona B. **Tracking a subset of skeleton joints - An effective approach towards complex human activity recognition**, Journal of Robotics, vol. 2017, DOI:10.1155/2017/7610417
3. Russo L.O., Rosa S., Maggiora M., Bona B. **A Novel Cloud Based Service Robotics Application to Data Center Environmental Monitoring**, Sensors, 2016, DOI: 10.3390/s16081255
4. Russo L.O., Farulla G., Pianu D., Salgarella A., Controzzi M., Cipriani C., Oddo C., Geraci C., Rosa S., Indaco M., **PARLOMA - a remote communication system for deafblind persons by means of gesture recognition**, International Journal of Advanced Robotic Systems, 2015, ISSN: 1729-8806, DOI: 10.5772/60416
5. Ermacora G., Rosa S., Toma A., **Fly4SmartCity: a Cloud Robotics Service for Smart City Applications**, Journal of Ambient Intelligence and Smart Environments, 2016, DOI: 10.3233/AIS-160374

6. Bona B., Carlone L., Indri M., Rosa S., **Supervision and monitoring of logistic spaces by a cooperative robotic team: methodologies, problems, and solutions**, Intelligent Service Robotics, 2014, DOI: 10.1007/s11370-014-0151-0
7. Abrate F., Bona B., Indri M., Rosa S., Tibaldi F., **Multirobot Localization in Highly Symmetric Environments**, Journal of Intelligent and Robotic Systems, 2013, DOI: 10.1007/s10846-012-9790-6
8. Abrate F., Bona B., Indri M., Rosa S., Tibaldi F., **Multi-robot map updating in dynamic environments**, in Springer Tracts in Advanced Robotics, Volume 83, 2013, DOI: 10.1007/978-3-642-32723-0

Conference papers

1. Rosa S., Wang Z., Yang B., Linhai X., Wang S., Markham A., Trigoni N., **Defo-Net: Learning Body Deformation using Generative Adversarial Networks**, accepted, ICRA 2018
2. Linhai X., Wang S., Rosa S., Trigoni N., **Learning with Training Wheels: Speeding up Training with a Simple Controller for Deep Reinforcement Learning**, accepted, ICRA 2018
3. Lu X., Kan X., Rosa S., Wen H., Markham A., Trigoni N., **Towards Self-supervised Face Labeling via Cross-modality Association**, poster, SenSys 2017, The Netherlands
4. Rosa S., Lu X., Wen H., Trigoni N., **Leveraging User Activities and Mobile Robots for Semantic Mapping and User Localization**. HRI 2017 Late Breaking Reports, Vienna
5. Rosa S., Toscana G. **Fast Feature-Less Quaternion-based Particle Swarm Optimization for Rigid and Articulated Pose Estimation From RGB-D Images**, ECCV 2016, R6D2016 Workshop, Amsterdam, NL
6. Toscana G., Rosa S., **Fast Feature-Less Quaternion-based Particle Swarm Optimization for Object Pose Estimation From RGB-D Images**, BMVC 2016, York, UK
7. Rosa S., Toscana G., **Fast Graph-Based Object Segmentation for RGB-D Images**, Intellisys 2016, London, UK
8. Rosa S., Russo L.O., Toscana G., Primatesta S., Kaouk Ng M., Bona B., **Leveraging the Cloud for Connected Service Robotics Applications**, Workshop on Robotics and Technology Transfer, ETFA 2015, Luxemburg, LU

9. B. de Gusmao P.B., Rosa S., Magli E., Lepsøy S., Francini L., **Robotics Navigation Using MPEG CDVS**, 17th International Workshop on Multimedia Signal Processing, MMSP 2015, Xiamen, China
10. Rosa S., Russo L.O., Bona B., **Towards A ROS-Based Autonomous Cloud Robotics Platform for Data Center Monitoring**. In: the 19th IEEE International Conference on Emerging Technologies and Factory Automation (ETFA), Barcelona, Spain, 2014
11. Lupetti M.L., Rosa S., Ermacora G., **From a Robotic Vacuum Cleaner to Robot Companion: Acceptance and Engagement in Domestic Environments**. HRI (Extended Abstracts) 2015
12. Ermacora G., Toma A., Rosa S., Antonini R., **A cloud based service for management and planning of autonomous UAV missions in smartcity scenario**. MESAS-14, May 5 - 6, 2014, Roma, Italy
13. Ermacora G., Toma A., Rosa S., Antonini R., **Leveraging open data for supporting a cloud robotics service in a smart city environment**. IAS-13, July 15 - 19, 2014, Padova, Italy
14. Rosa S., Russo L.O., Airò Farulla G., Antonini R., Gaspardone M., Carlone L., Bona B., **An Application of Laser-Based Autonomous Navigation for Data-Center Monitoring**. IAS-13, July 15 - 19, 2014, Padova, Italy
15. Yuan Z., Rosa S., Russo L.O., Bona B., **A Kinect-based Front-end for Graph-SLAM Using Plane Matching in Planar Indoor Environments**. IAS-13, July 15 - 19, 2014, Padova, Italy
16. Anjum M., Ahmad O., Rosa S., Yin J., Bona B., **Skeleton Tracking Based Complex Human Activity Recognition Using Kinect Camera**. In: Social Robotics / Beetz, Springer International Publishing, pp. 23-33. ISBN 9783319119724
17. Airo Farulla G., Russo L.O., Pintor C., Pianu D., Micotti G., Salgarella A.R., Camboni D., Controzzi M., Cipriani C., Oddo C.M., Rosa S., Indaco M., **Real-time single camera hand gesture recognition system for remote deaf-blind communication**. In: 1st International Conference on Augmented and Virtual Reality, Lecce, 17-20 September 2014.
18. Yin J., Carlone L., Rosa S., Anjum M.L., Bona B., **Scan Matching for Graph SLAM in Indoor Dynamic Scenarios**, 27th International FLAIRS Conference, May 21 - 23, 2014, Pensacola Beach, Florida, USA
19. Russo L.O., Rosa S., Matteucci M., Bona B., **A ROS Implementation of the Mono-SLAM Algorithm**, International Conference on Artificial Intelligence & Applications (ARIA-2014), 2014

20. Russo L.O., Airò farulla G., Indaco M., Rosa S., Rolfo D., Bona B., **Blurring prediction in Monocular SLAM**, 8th IEEE International Design & Test Symposium 2013 (IDT), 2013
21. L. Carlone, J. Yin, S. Rosa, Z. Yuan, **Graph optimization with unstructured covariance: fast, accurate, linear approximation.** In: Simulation, Modeling, and Programming for Autonomous Robots (SIMPAN 2012), 2012.
22. Rosa S., Paleari M., Ariano P., Bona B., **Object Tracking with Adaptive HOG Detector and Adaptive Rao-Blackwellised Particle Filter.** In: SPIE 8301, Intelligent Robots and Computer Vision XXIX: Algorithms and Techniques, 2012.
23. Paleari M., Margaria V., Rosa S., Ariano P., **HEXEC: hand exoskeleton electromyographic control**, 4th International Workshop on Human-Friendly Robotics (HFR 2011), University of Twente, The Netherlands
24. Macchia V.; Rosa S; Carlone L; Bona B., **An Application of Omnidirectional Vision to Grid-based SLAM in Indoor Environments.** In: Workshop on Omnidirectional Robot Vision, International Conference on Robotics and Automation (ICRA 2010), 2010.
25. Abrate F; Bona B; Indri M; Rosa S.; Tibaldi F., **Map updating in dynamic environments.** In: ISR/ROBOTIK 2010, 2010.
26. Brevi D., Fileppo F. , Scopigno R. , Abrate F., Bona B., Rosa S., Tibaldi F., **Hybrid localization solutions for robotic logistic applications.** In: Technologies for Practical Robot Applications (TePRA), 2009.
27. Abrate F; Bona B.; Indri M; Rosa S; Tibaldi F., **Three-State Multirobot Collaborative Localization in Symmetrical Environments.** In: ROBOTICA 2009, 2009
28. Abrate F; Bona B; Indri M.; Rosa S; Tibaldi F., **Switching Multirobot Collaborative Localization in Symmetrical Environments.** In: IROS 2008 2nd Workshop on Planning, Perception and Navigation for Intelligent Vehicles, 2008.

Links

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